

L2G-Net: Local to Global Spectral GNNs via Cauchy Factorizations

S. Fernández Mendiña, E. Pavez, A. Ortega

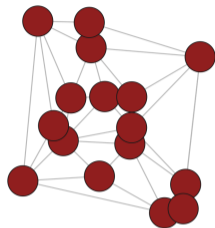
University of Southern California



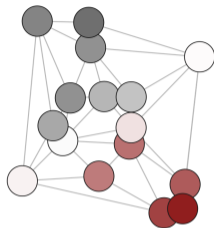
Overview

- GNNs and GFT
- Cauchy matrices and Cauchy factorization
- L2G-Net
- Empirical results
- Conclusions and future work

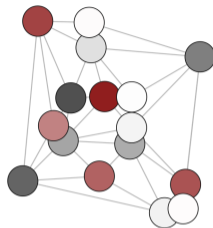
Spectral GNNs and the GFT



$\lambda = 0.00$



$\lambda = 0.33$



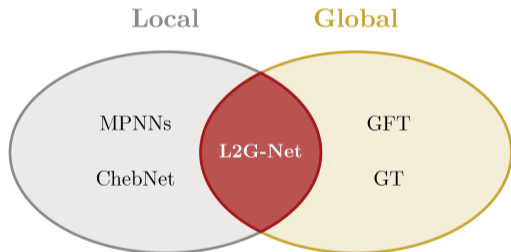
$\lambda = 1.57$

Graph Fourier transform (GFT) [Ortega et al., 2018]: meaningful frequencies.

Cubic complexity $O(n^3) \implies$ impractical for large graphs.

Fully global \implies no local inductive bias for short-range tasks.

Existing approaches



- **MPNNs** [Kipf and Welling, 2017] and **polynomial filters** [Defferrard et al., 2016]: local, but oversquashing, instabilities.
- **Graph transformers** [Dwivedi and Bresson, 2021]: global, but many parameters, lose topological inductive bias.
- Our goal: **GFT** without cubic complexity and **local-to-global** processing.

Our contribution

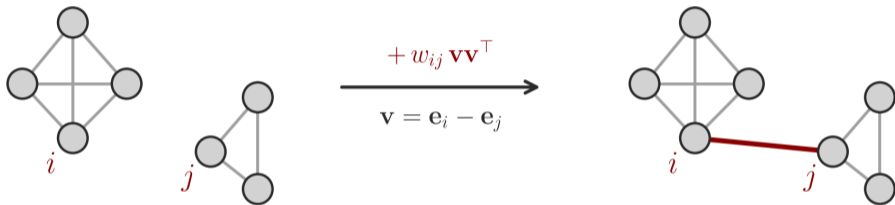
We introduce an **exact factorization** of the GFT via Cauchy matrices.

- 1) **Quadratic complexity** $O(kn^2)$ scaled by the subgraph cut size.
- 2) **Graph partitioning** algorithm to minimize factorization cost.
- 3) **L2G-Net**: a new class of spectral GNNs with local-to-global bias.

Background: rank-one updates and Cauchy matrices

Adding an edge (i, j) to a graph yields a **rank-one update** of the Laplacian \mathbf{L} :

$$\tilde{\mathbf{L}} = \mathbf{L} + w_{ij} \mathbf{v}\mathbf{v}^\top, \quad \mathbf{v} = \mathbf{e}_i - \mathbf{e}_j. \quad (1)$$



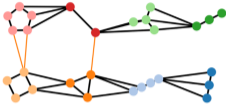
Cauchy update of the eigenbasis [Fernández et al., 2025]

Rank-one update \implies rotate by an **orthogonal Cauchy-like matrix**:

$$\tilde{\mathbf{U}}^\top = \mathbf{C}(\tilde{\boldsymbol{\lambda}}, \boldsymbol{\lambda}) \mathbf{U}^\top. \quad (2)$$

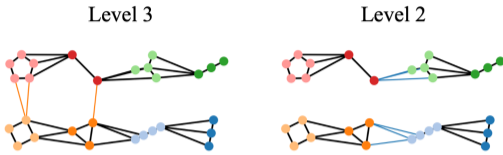
GFT via divide and conquer

Level 3



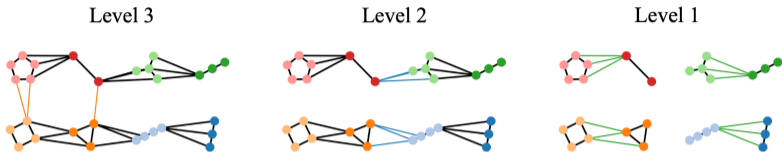
1 **Partition** the graph into subgraphs (e.g., balanced cuts).

GFT via divide and conquer



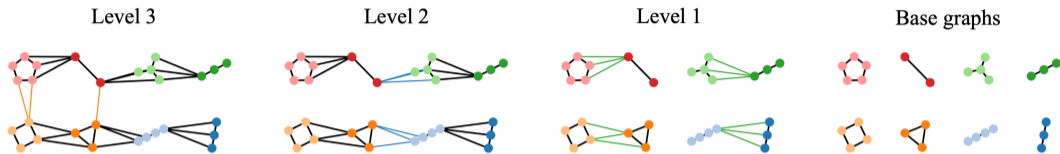
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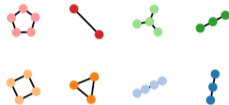
GFT via divide and conquer



- 1 **Partition** the graph into subgraphs (e.g., balanced cuts).
- 2 **Compute** GFT of base graphs.

GFT via divide and conquer

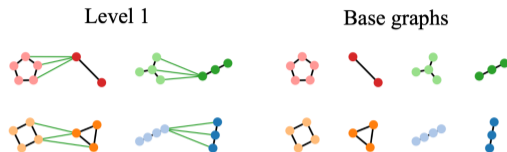
Base graphs



- 1 **Partition** the graph into subgraphs (e.g., balanced cuts).
- 2 **Compute** GFT of base graphs.
- 3 Progressively **merge** base GFTs using edge information.

Key: adding one edge adds one Cauchy factor [Fernández et al., 2025].

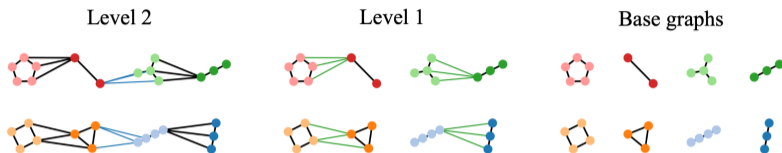
GFT via divide and conquer



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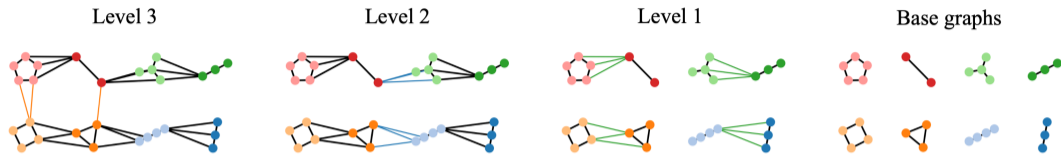
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Cauchy factorization of the GFT

GFT factorization

For any graph \mathcal{G} with GFT basis \mathbf{U}^\top :

$$\mathbf{U}^\top = \mathbf{D}(\boldsymbol{\lambda}, \tilde{\boldsymbol{\lambda}}_{K-1}) \cdots \mathbf{D}(\tilde{\boldsymbol{\lambda}}_1, \tilde{\boldsymbol{\lambda}}_0) \mathbf{U}_0^\top. \quad (3)$$

Start from **independent subgraph GFTs**, merge one cut edge at a time.

Each Cauchy factor is **localized** to the two subgraphs it connects.

Computable in **quadratic time**: $O(kn^2)$.

Similar eigenvalues

Orthogonal Cauchy-like matrices

Let $\mathbf{L} = \mathbf{U}\text{diag}(\boldsymbol{\lambda})\mathbf{U}^\top$ and $\tilde{\mathbf{L}} = \mathbf{L} + \rho \mathbf{v}\mathbf{v}^\top = \tilde{\mathbf{U}}\text{diag}(\tilde{\boldsymbol{\lambda}})\tilde{\mathbf{U}}^\top$. Then,

$$\tilde{\mathbf{U}}^\top = -\text{diag}(\mathbf{a})\mathbf{C}(\tilde{\boldsymbol{\lambda}}, \boldsymbol{\lambda})\text{diag}(\mathbf{z})\mathbf{U}^\top, \quad (4)$$

where $\mathbf{z} \doteq \mathbf{U}^\top \mathbf{v}$ and $\mathbf{a} \in \mathbb{R}^n$ normalizes each column.

Same eigenvalues after update \implies eigenvectors remain the same (deflation).

Eigenvalues are close \implies numerator and denominator decrease equally fast.

Operation is numerically well-conditioned.

Finding the new eigenvalues

Eigenvalue interleaving

Let $\mathbf{L} = \mathbf{U}\text{diag}(\boldsymbol{\lambda})\mathbf{U}^\top$ and $\tilde{\mathbf{L}} = \mathbf{L} + \rho \mathbf{v}\mathbf{v}^\top = \tilde{\mathbf{U}}\text{diag}(\tilde{\boldsymbol{\lambda}})\tilde{\mathbf{U}}^\top$. Then, if $\rho > 0$,

$$\lambda_1 \leq \tilde{\lambda}_1 \leq \lambda_2 \leq \dots \leq \lambda_n \leq \tilde{\lambda}_n, \quad (5)$$

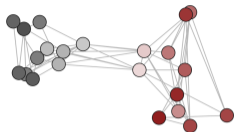
with the inequalities reversed when $\rho < 0$.

Given $\mathbf{z} = \mathbf{U}^\top \mathbf{v}$, it can be shown that the new eigenvalues are the roots of

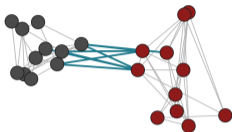
$$1 + \rho \sum_{i=1}^n z_i^2 / (\tilde{\lambda}_j - \lambda_i) = 0. \quad (6)$$

Solved efficiently using Netwon's method [Gu and Eisenstat, 1996].

Finding a suitable hierarchy



Fiedler vector



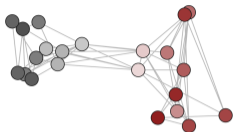
Partition: 8 bridge edges

We want small k . **Balanced cuts** via spectral bisection (Fiedler vector).

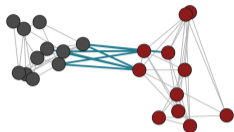
Accept partition only if theoretical complexity reduces.

Cut sparsification: reduce k via sparsification [Spielman and Srivastava, 2008].

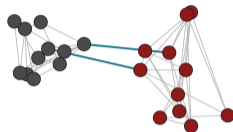
Finding a suitable hierarchy



Fiedler vector



Partition: 8 bridge edges



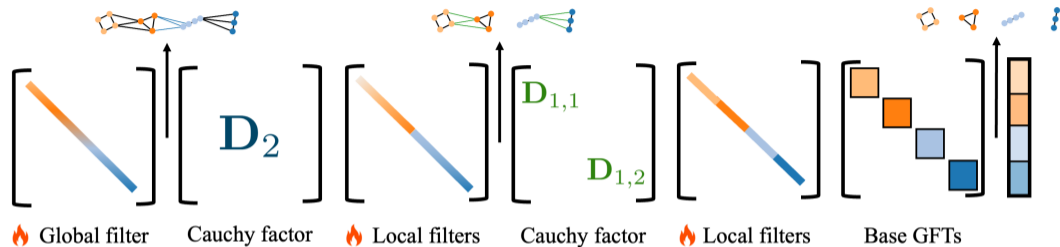
Sparsified: 2 bridge edges

We want small k . **Balanced cuts** via spectral bisection (Fiedler vector).

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Cut sparsification: reduce k via sparsification [Spielman and Srivastava, 2008].

L2G-Net architecture



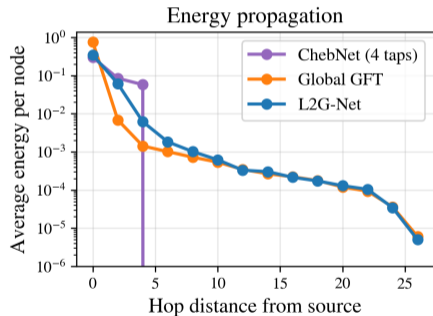
Local filters capture patterns within subgraphs.

Global filter models long-range subgraph interactions.

Intuition: architecture **adapts to graph structure** before training begins.

L2G-Net: inductive bias

L2G-Net provides a trade-off between MPNN locality and GFT globality.

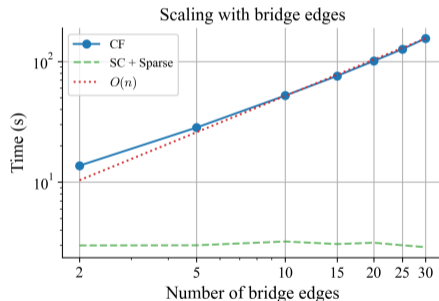
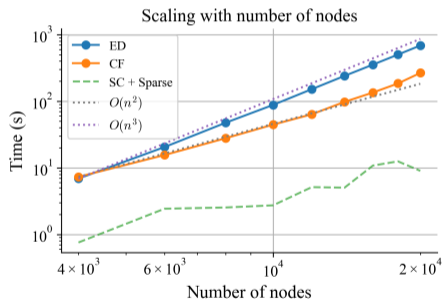


- Insert an impulse in a node.
- Apply the operator. Use randomly initialized filters.
- Measure energy k -hops away.
- Average over random filters.

Empirical complexity validation

Compute eigendecomposition (ED) and Cauchy Factorization (CF).

Barabási–Albert random graphs.



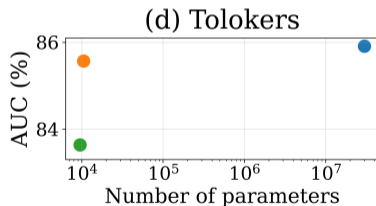
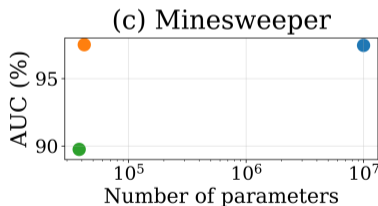
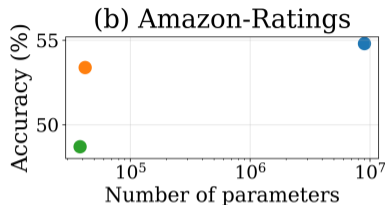
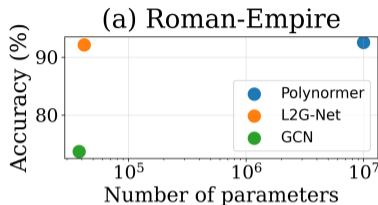
Runtime scales as $O(n^2)$ and $O(k)$, matching theoretical predictions.

Experimental setup

We test L2G-Net in:

- A transductive benchmark for heterophilous graphs [Platonov et al., 2023].
Quantifies performance against graph transformers.
- A transductive benchmark of large scale graphs.
Demonstrates L2G-Net scales to graphs beyond reach for the GFT.
- Inductive tasks on small graphs.
Tests L2G-Net in graph-level benchmarks.

GNNs in [Platonov et al., 2023]

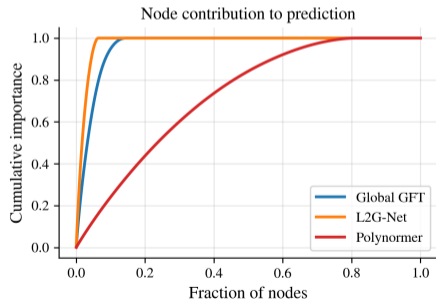


Similar or better performance than Polynormer, same parameters as GCN.

Graph topology

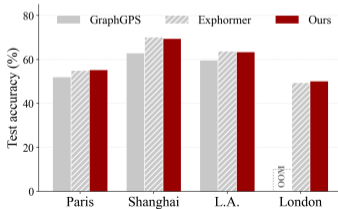
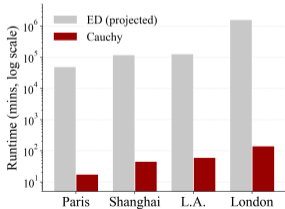
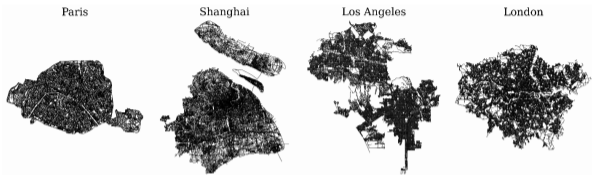
L2G-Net has more graph localization than GFT.

L2G-Net exploits better the graph topology than Polynormer.



- Task: node classification.
- Use GradCAM to measure how many nodes contribute to prediction.
- Compute cumulative plot of contributions.

GNNs in CityNetworks [Liang et al., 2025]

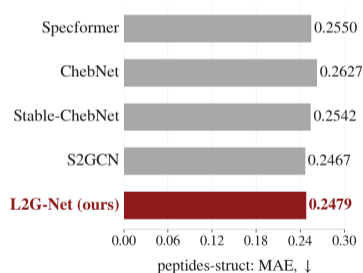
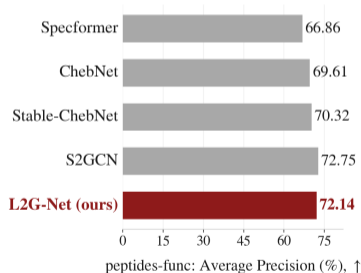
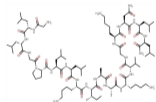


- **Global:** Estimate eccentricity of each node.
- Scales to graphs where GFT is unfeasible.
- Matches performance with less parameters.

GNNs in drug discovery [Dwivedi et al., 2022]

Global: chemical properties depend on **interactions across the whole molecule**.

Local: **functional groups** govern short-range chemistry.



L2G-Net **captures both regimes** with a single architecture.

Conclusions and future work

L2G-Net: **exact GFT** with **local-to-global** inductive bias.

Cauchy factorization reduces complexity from $O(n^3)$ to $O(kn^2)$.

- Competitive accuracy with far fewer parameters.

Future work:

- Extension to **directed and dynamic graphs**.

Questions? samuelf9@usc.edu

Webpage: https://sf219.github.io/L2G_NET/



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