

# Processing Probabilistic Signals on Causal Abstraction Networks

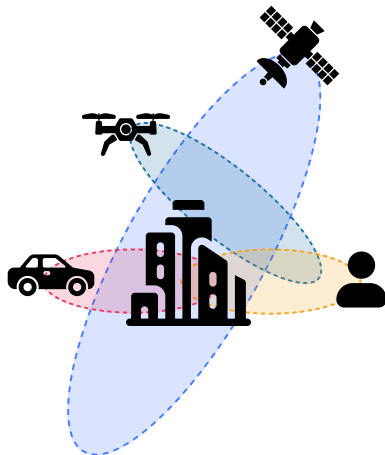
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Modern networked systems involve **heterogeneous agents** that:

- ▶ Observe the same environment **partially** and at **different resolutions**
- ▶ Build **local models** shaped by their interactions
- ▶ Must **collaborate** despite heterogeneous perspectives



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Richens & Everitt (2024). *Robust agents learn causal world models*. ICLR.

Richens, Everitt, Abel (2025). *General agents need world models*. ICML.

Bareimboim (2025). *Causal Artificial Intelligence: A Roadmap for Building Causally Intelligent Systems*. Online (draft version).

## Representation

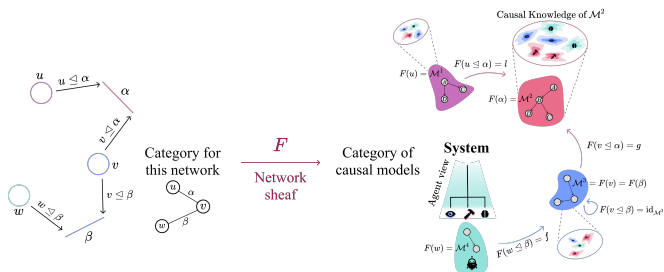
How to **formally organize** heterogeneous local models over a network?

## Diffusion & Alignment

How does local knowledge **evolve, propagate, and align** across agents?

## Learning

How to **learn** the representation model from data alone?

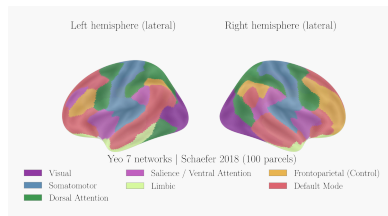


*A network sheaf organizes local causal models into a principled, globally consistent structure. It attaches causal models to nodes and edges of the network, and causal abstractions to node-edge incidence relations*

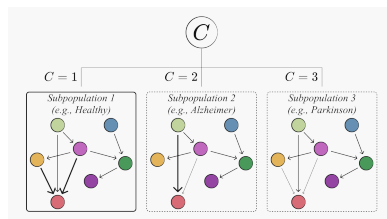
D'Acunto & Battiloro (2025). *The Relativity of Causal Knowledge*. UAI.

Fritz (2009). *Convex spaces I: Definition and examples*. ArXiv.

Pearl (2009). *Causality*. Cambridge university press.



(a) System



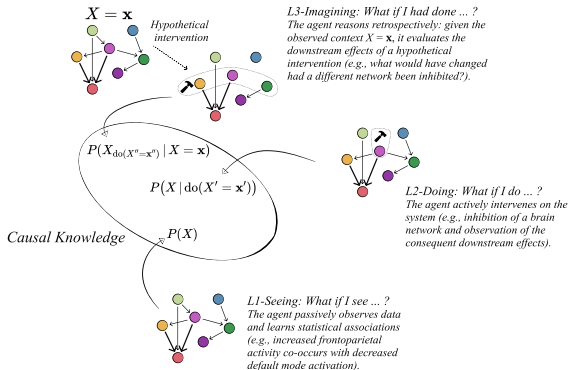
(b) Mixture Causal Model

*Each agent holds a local mixture causal model: a probabilistic, context-dependent subjective belief of the system*

Pearl (2009). *Causality*. Cambridge University Press.

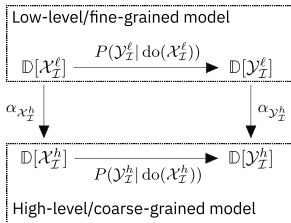
Geiger & Heckerman (1996). *Knowledge representation and inference in similarity networks and Bayesian multinets*. Artificial Intelligence.

Thiesson, Meek, Chickering, Heckerman (2013). *Learning mixtures of DAG models*. UAI.

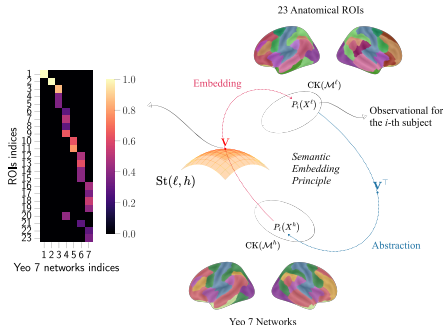


An MCM supports reasoning at all three levels of Pearl's causal hierarchy: seeing, doing, and imagining

Recall  $\text{St}(d_i, d_j) := \{\mathbf{V}_{ij} \in \mathbb{R}^{d_i \times d_j} \mid \mathbf{V}_{ij}^\top \mathbf{V}_{ij} = \mathbf{I}_{d_j}\}$



(c)  $\alpha := \langle \mathcal{R}, m, \alpha \rangle$



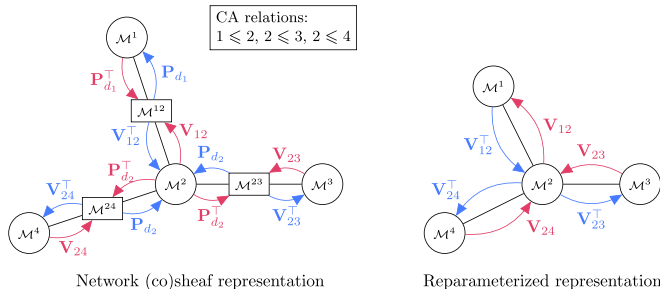
(d) Constructive Linear CA

*Causal abstractions formalize interventionally consistent mappings between causal models of the same system working at different levels of granularity*

Beckers & Halpern (2019). *Abstracting causal models*. AAAI.

Rischel & Weichwald (2021). *Compositional abstraction error*. UAI.

D'Acunto, Zennaro, Felekis, Di Lorenzo (2025). *Causal Abstraction Learning based on the semantic embedding principle*. ICML.



*CAN synthesizes the network sheaf (from node to edges) and cosheaf (from edges to nodes) using constructive linear abstractions as transport maps. Reparameterization can be exploited.*

D'Acunto, Di Lorenzo, Barbarossa (2026). *Networks of causal abstractions: A sheaf-theoretic framework*. ArXiv.

► Sheaf signal:

$$\mathcal{P}_0 = \{P(X^1)^0, \dots, P(X^N)^0\}$$

► Laplacian

$$\mathcal{L} : \mathcal{C}^0(\mathcal{G}; E) \rightarrow \mathcal{C}^0(\mathcal{G}; E),$$

$$\mathcal{L} = \delta^* \circ \delta$$

Algebraic representation  $\mathbb{L}$

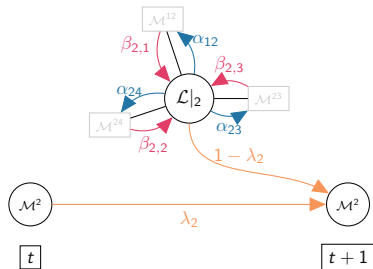
► Coboundary

$$\delta : \mathcal{C}^0(\mathcal{G}; E) \rightarrow \mathcal{C}^1(\mathcal{G}; E);$$

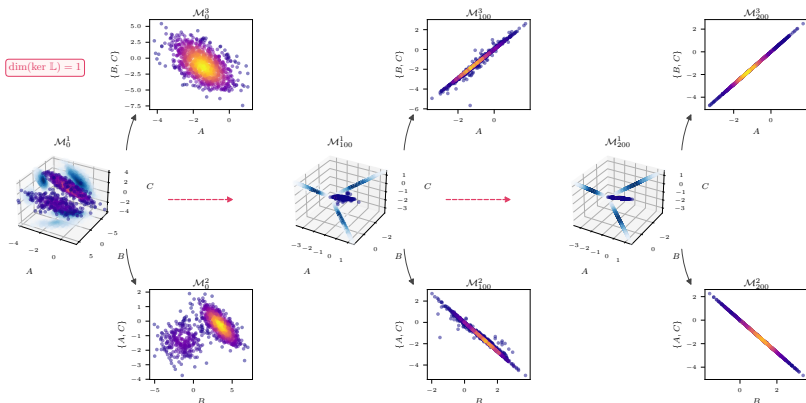
$$\delta(\mathcal{P})|_{e_{ij}} = cc_{\alpha_e}(P(X^i), P_{V_{ij}}(X^j))$$

► Boundary

$$\delta^* : \mathcal{C}^1(\mathcal{G}; E) \rightarrow \mathcal{C}^0(\mathcal{G}; E)$$



$$\mathcal{P}_{t+1} = cc_{\lambda}(\mathcal{P}_t, \mathcal{L}(\mathcal{P}_t))$$



*The nonlinear sheaf Laplacian drives local distributions toward a common one-dimensional latent subspace ( $\dim(\ker \mathbb{L}) = 1$ ): the space of global sections*

- ▶ We work in non-Euclidean setting
- ▶  $P(X^i)$  ( $d_i$ -dimensional),  $P(X^j)$  ( $d_j$ -dimensional),  $d_i > d_j$
- ▶ Is  $P(X^j)$  a constructive linear abstraction of  $P(X^i)$ ?
- ▶  $D_{\mathbf{V}_{ij}^\top}(P(X^j), P(X^i))$ 
  - ▶ Gaussian setting:  $\text{KL}(P(X^j) || P_{\mathbf{V}_{ij}^\top}(X^i))$
  - ▶ Mixtures of Gaussians:  $\text{MPW}_2(P(X^i), P(X^j))$

$$\text{MPW}_2(P(X^i), P(X^j)) := \inf_{\substack{\Omega \in \Pi(\mathbf{w}_i, \mathbf{w}_j) \\ \mathbf{V}_{ij} \in \text{St}(d_i, d_j)}} \sum_{\substack{p \in [I] \\ q \in [J]}} \omega_{pq} W_2^2(P_{\mathbf{V}_{ij}^\top}(X^{(i,p)}), P(X^{(j,q)}))$$

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D'Acunto, Zennaro, Felekis, Di Lorenzo (2025). *Causal Abstraction Learning based on the semantic embedding principle*. ICML.

Cai & Lim (2022). *Distances between probability distributions of different dimensions*. IEEE Transactions on Information Theory.

Salmona, Desolneux, Delon (2024). *Gromov-Wasserstein-like Distances in the Gaussian Mixture Models Space*. TMLR.

- ▶ Smoothness:

$$f(\mathcal{E}, \{\mathbf{V}_{ij}^\top\}) = \sum_{e_{ij} \in \mathcal{E}} D_{\mathbf{V}_{ij}^\top}(P(X^j), P(X^i))$$

- ▶ Global section condition:

$$P(X^i) = P_{\mathbf{V}_{ij}}(X^j), \quad \mathbf{V}_{ij} \in \text{St}(d_i, d_j), \quad \forall e_{ij} \in \mathcal{E}$$

- ▶ *Global alignment*  $\implies$  *Smoothness* (the converse does not hold)

- ▶ Global nonconvex learning problem:

$$\max_{\mathcal{E} \subseteq \mathcal{F}} |\mathcal{E}|$$

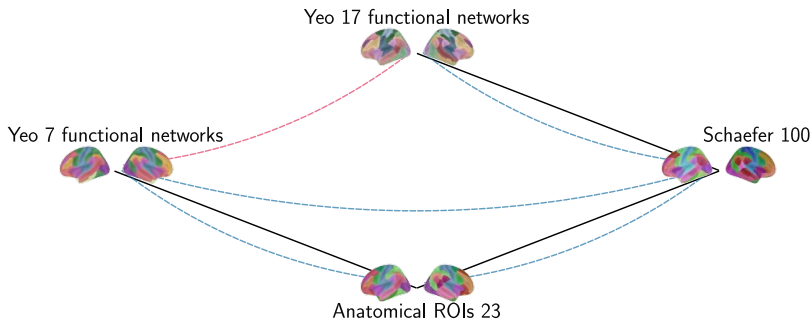
subject to 
$$\inf_{\substack{\Omega \in \Pi(\mathbf{w}_i, \mathbf{w}_j) \\ \mathbf{V}_{ij} \in \text{St}(d_i, d_j)}} \text{MPW}_2(P(X^i), P(X^j)) \leq \tau_{\text{MPW}}, \quad \forall e_{ij} \in \mathcal{E}.$$

- ▶ Search procedure over the candidate edges that exploits CLCA compositionality
- ▶ Local problems solved in alternating fashion over  $\Omega$  (entropic OT) and  $\mathbf{V}_{ij}$  (first-order Riemannian optimization)

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Peyré & Cuturi (2019). *Computational optimal transport: With applications to data science*. Now Foundations and Trends.

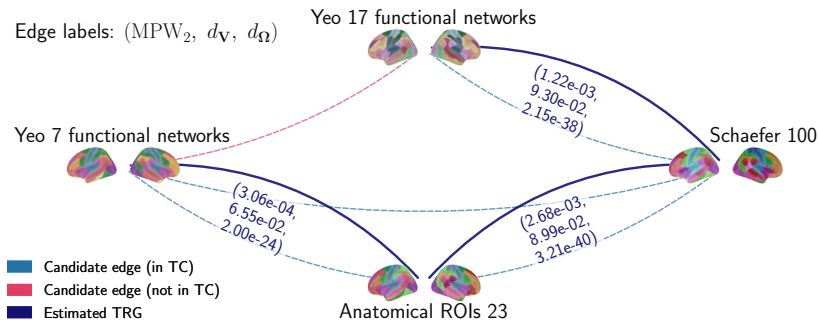
Lai & Osher (2014). *A splitting method for orthogonality constrained problems*. *Journal of Scientific Computing*.



- ▶ Preprocessed multi-task HCP data, 100 healthy subjects
- ▶ Gaussian mixture models fitted at the granularity Schaefer 100 via EM and cross-validation
- ▶ Candidate edges (dashed) according to spectral interlacing necessary condition for the existence of causal abstractions

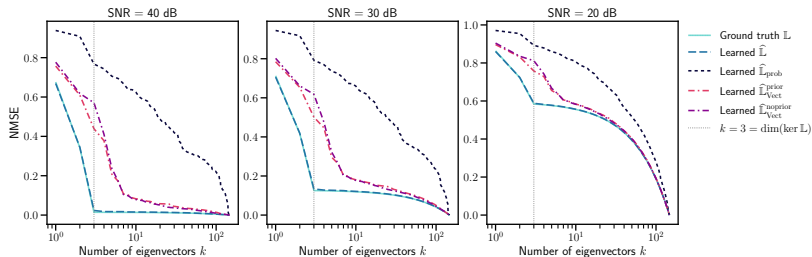
D'Acunto, Di Lorenzo, Barbarossa. (2026) *Multi-agent SCMs: From local to global knowledge via a sheaf-theoretic framework*. Submitted.

Santoro, Battiston, Petri, Amico (2023). *Higher-order organization of multivariate time series*. Nature Physics.



- Our learning algorithm recovers the ground-truth V-shape topology and the CLCA maps from observational fMRI data alone

- ▶ Perturbed global section  $\mathcal{P} \in \mathbb{R}^{147 \times 162100}$  at varying degree of noise
- ▶ Baselines: learned sheaf Laplacian in  $\text{Vect}_{\mathbb{R}}$  with/without topological prior, learned sheaf Laplacian in CSprob (dense Stiefel maps)



## Representation

### Causal Abstraction Network

- ▶ Nodes and edges: Convex spaces of probability distributions
- ▶ Transport maps: constructive linear causal abstractions and their transpose

## Diffusion & Alignment

### Nonlinear sheaf Laplacian $\mathcal{L}$

- ▶ Featured by hyper-parameters
- ▶ Spectral characterization via  $\mathbb{L}$
- ▶ Convergent discrete-time dynamics under mild conditions

## Learning

### Framework based on smoothness functional

- ▶ Separable over the edges
- ▶ Exploiting compositionality of causal abstraction
- ▶ Amenable to different metrics, according to non-Euclidean setting